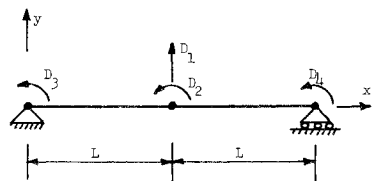


Fig. 1 Simply supported beam.



eliminating the two rotational degrees of freedom at the ends of the beam. Using the consistent mass and stiffness matrices for the beam elements² and the reduction method^{1,3} to eliminate degrees of freedom D_3 and D_4 , yields the eigenvalues

$$\omega_1^2 = (105/17)EI/\rho A L^4 \quad \omega_2^2 = 157.5 EI/\rho A L^4 \quad (4)$$

The auxiliary eigenvalue problem, Eq. (2), which establishes convergence of Eq. (1) yields the double root solution

$$\bar{\omega}_1^2 = \bar{\omega}_2^2 = 420 EI/\rho A L^4 \quad (5)$$

Clearly, the frequencies of Eq. (5) are all greater than the frequencies of Eq. (4); therefore, the series expansion of Eq. (1) will converge for each frequency of Eq. (4) and the reduction method has been properly used.

To recover the eliminated degrees of freedom, the back-transformation approximation, Eq. (3), is used and the resulting modal vectors are shown in Table 1 along with the modal

Table 1 Modal vectors for example problem of Fig. 1

Degree of freedom	Present analysis		Guyan method		Exact (Ref. 4)	
	first mode	second mode	first mode	second mode	first mode	second mode
1	1	0	1	0	1	0
2	0	1	0	1	0	1
3	1.5706/L	-1.0742	1.50/L	-0.50	1.5708/L	-1
4	-1.5706/L	-1.0742	-1.50/L	-0.50	-1.5708/L	-1

vectors obtained from the Guyan method³ and the exact method of Ref. 4. As can be seen from Table 1, the back-transformation of Eq. (3) produces excellent results: an error of -0.013% for the first mode and an error of +7.42% for the second mode. Without including the inertia terms in Eq. (3), which is the Guyan back-transformation, the errors are -4.5% and -50% for the first and second modes, respectively.

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Comment on "On Multiple-Shaker Resonance Testing"

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THE characteristic phase-lag method attributed by the author¹ to Bishop and Gladwell was first published in 1948² and influenced most of Traill-Nash's early work. Its application

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to multiple-shaker resonance testing was the subject of an AGARD report³ in which a principle of minimum reactive energy and the essentially equivalent complex admittance rule is demonstrated. The main result, however, is that, for a limited number of shakers and small enough damping, the forcing amplitude ratios should be such that phase resonance occurs at each shaking point.

The GRAMPA (and later MAMMA) multiple-shaker installation, described in the author's Ref. 6, was based on this result. The performance obtained at Royal Aircraft Establishment with this apparatus was so convincing that it would be interesting to compare this method of regulating the shaker amplitudes with the various approaches described in the article. It may also be mentioned that the characteristic phase-lag and damping theories, duly quoted in many books and articles on the subject of forced response of linear damped systems, were later enlarged and the subject of further publications.⁴⁻⁶

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Reply by Authors to B. Fraeijis de Veubeke

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THE authors express their appreciation to Fraeijis de Veubeke for supplying references to his own work on resonance testing. It was not the authors' intention to present a complete history of the development of resonance test methods. The Bishop and Gladwell reference¹ was quoted because it provides this background as well as an extensive list of references, including references to Fraeijis de Veubeke's 1948² and 1956³ works on the "characteristic phase lag theory."

The technique for determining excitation frequency and force amplitudes in a multiple-shaker test, referred to (perhaps erroneously) by the authors as the "Asher method," had been discussed by Fraeijis de Veubeke, Asher,⁴ and others. However, the authors sought, through use of a simulation study, to emphasize the fact that an insufficient number of shakers or an inappropriate group of shakers could produce spurious natural frequencies and unacceptable mode shapes, and to explore more

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thoroughly the effect of close spacing of natural frequencies. The authors hope that this simulation study provides some insight into the uses and limitations of the "Asher method" not heretofore available in the open literature.

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Errata

Dynamic Nonlinear Response of Cylindrical Shells to Asymmetric Pressure Loading

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THE potential energy of the external pressure given by Eq. (5) was formulated assuming a conservative force system. This assumption is incorrect, since that portion of pressure loading

associated with the force vector changing direction and magnitude as the shell deforms represents a nonconservative force system. Therefore, the generalized forces in the governing equations of motion given by Eq. (10) should have been derived through the principle of virtual work instead of from the potential function. Hence, the integrands of the generalized force quantities, \tilde{Q}_w , \tilde{Q}_v , and \tilde{Q}_u , obtained through the virtual work method replace Eq. (11) in the following form:

$$\begin{aligned} -\tilde{Q}_w &= 2L^2Rp \left(-1 + \bar{W} + W - V_\theta - \frac{1}{L} U_\gamma \right) \frac{\partial W}{\partial W_{mn}} \\ -\tilde{Q}_v &= 2L^2Rp(W_\theta + \bar{W}_\theta + V) \frac{\partial V}{\partial V_{mn}} \\ -\tilde{Q}_u &= 2LRp(W_\gamma + \bar{W}_\gamma) \frac{\partial U}{\partial U_{mn}} \end{aligned}$$

This correction primarily affects large displacement response and results in a reduction of the peak response quantities by about 19, 10, and 6% at load levels of $p_r = 150$, 125, and 100 psi, respectively, for shell B in Fig. 3.

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